

$\{q_i\}, \{p_i\} \longrightarrow \{Q_i\}, \{P_i\}$ Canonical

Generating Functions for Canonical Transformations

Principle of least action for old variables:

$$0 = \int_{t_1}^{t_2} dt \left\{ \sum_i p_i \dot{q}_i - H(\{p_i\}, \{q_i\}, t) \right\}, \quad \begin{array}{l} q_i(t_1) \text{ fixed} \\ q_i(t_2) \text{ fixed} \end{array}$$

for the new ones:

$$0 = \int_{t_1}^{t_2} dt \left\{ \sum_i P_i \dot{Q}_i - H'(\{P_i\}, \{Q_i\}, t) \right\}, \quad \begin{array}{l} Q_i(t_1) \text{ fixed} \\ Q_i(t_2) \text{ fixed} \end{array}$$

these must be equivalent \longrightarrow

$$\sum_i p_i \dot{q}_i - H(\{p_i\}, \{q_i\}, t) = \sum_i P_i \dot{Q}_i - H'(\{P_i\}, \{Q_i\}, t) + \frac{d}{dt} F(\{q_i\}, \{Q_i\}, t)$$

$$dF = \sum_i p_i dq_i - \sum_i P_i dQ_i + (H' - H) dt$$

$$p_i = \frac{\partial F}{\partial q_i}$$

$$\frac{\partial F}{\partial t} = H' - H$$

$$-P_i = \frac{\partial F}{\partial Q_i}$$

F is called
generating
function

$$\text{Example: } F = \sum_i q_i Q_i$$

$$p_i = \frac{\partial F}{\partial q_i} = Q_i \quad P_i = -\frac{\partial F}{\partial Q_i} = -q_i$$

just exchange
positions &
momenta!

Other generating functions via Legendre transforms

$$\text{Example: } G := F + \sum_i P_i Q_i$$

$$dG = dF + \sum_i P_i dQ_i + \sum_i Q_i dP_i =$$

$$= \sum_i p_i dq_i - \sum_i P_i dQ_i + (H' - H) dt + \sum_i P_i dQ_i + \sum_i Q_i dP_i =$$

$$dG = \sum_i p_i dq_i + \sum_i Q_i dP_i + (H' - H) dt$$

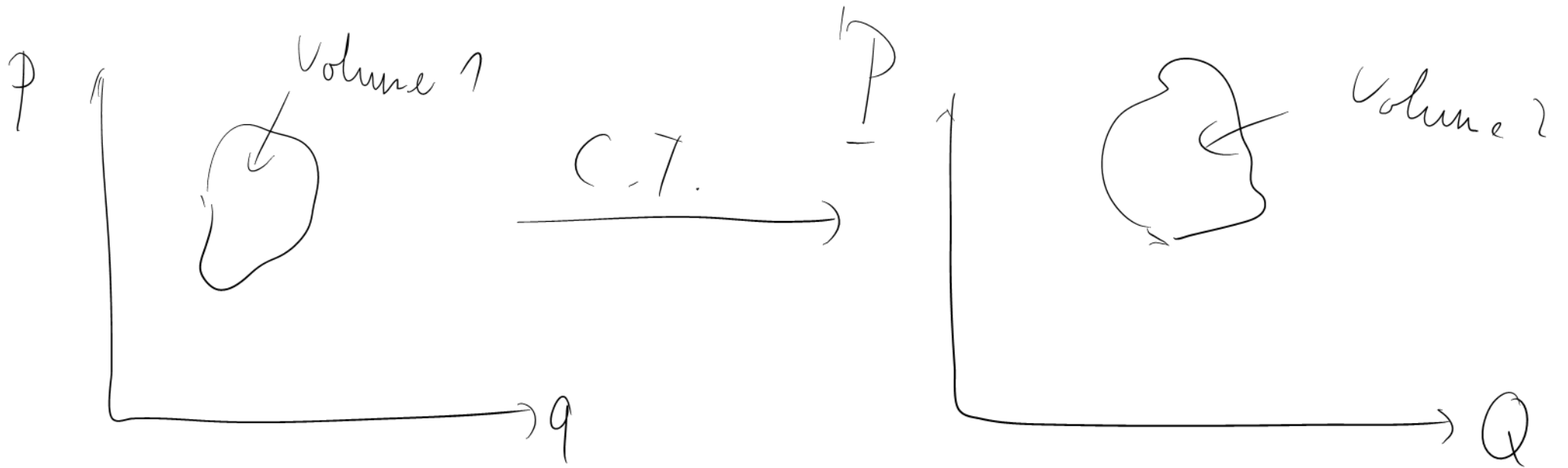
$$p_i = \frac{\partial G}{\partial q_i} \quad Q_i = \frac{\partial G}{\partial P_i} \quad H' = H + \frac{\partial G}{\partial t}$$

Example: $G = \sum_i q_i P_i \Rightarrow p_i = P_i, Q_i = q_i$

generates the identical transformation!

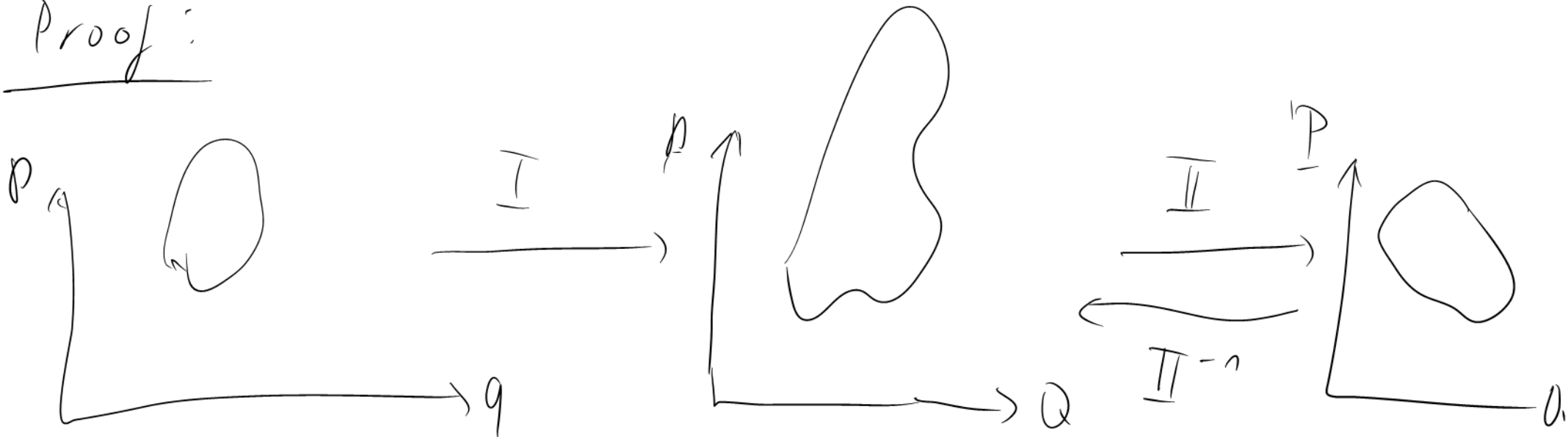
Phase Space Volume is INVARIANT under

Canonical Transformations



Claim: Volume 1 = Volume 2

Proof:



Distortion factor for the volume:

Determinant of the Jacobian:

$$\left. \begin{array}{l} \text{I: } \det \left(\frac{\partial Q_i}{\partial q_j} \right) \\ \text{II: } \det \left(\frac{\partial p_i}{\partial P_j} \right) \end{array} \right\} \text{claim: } \det \left(\frac{\partial Q_i}{\partial q_j} \right) = \det \left(\frac{\partial p_i}{\partial P_j} \right)$$

Use generating function $G(q, \{P, \})$:

$$Q_i = \frac{\partial G}{\partial P_i} \Rightarrow \frac{\partial Q_i}{\partial q_j} = \frac{\partial^2 G}{\partial P_i \partial q_j}$$

$$P_i = \frac{\partial G}{\partial q_i} \Rightarrow \frac{\partial P_i}{\partial P_j} = \frac{\partial^2 G}{\partial P_j \partial q_i}$$

→ matrices are transposed wrt each other

→ determinants are the same!



Infinitesimal Canonical Transformations

$$G(\{q_i\}, \{p_i\}) = \sum_i q_i p_i + \varepsilon \sigma(\{q_i\}, \{p_i\}) + O(\varepsilon^2)$$

ε small, $\varepsilon \rightarrow 0$

$$P_i = \frac{\partial G}{\partial q_i} = p_i + \varepsilon \frac{\partial \sigma}{\partial q_i} + O(\varepsilon^2) \approx$$

$$\approx p_i + \varepsilon \frac{\partial}{\partial q_i} \sigma(\{q_i\}, \{p_i\}) + O(\varepsilon^2)$$

$$Q_i = \frac{\partial G}{\partial p_i} = q_i + \varepsilon \frac{\partial \sigma}{\partial p_i} + O(\varepsilon^2) \approx$$

$$\approx q_i + \varepsilon \frac{\partial}{\partial p_i} \sigma(\{q_i\}, \{p_i\}) + O(\varepsilon^2)$$

$$P_i = p_i - \varepsilon \frac{\partial}{\partial q_i} \sigma(\{q_i\}, \{p_i\}) + O(\varepsilon^2)$$

$$Q_i = q_i + \varepsilon \frac{\partial}{\partial p_i} \sigma(\{q_i\}, \{p_i\}) + O(\varepsilon^2)$$

Consider now the actual time development

$$q_i(t) \equiv q_i \longrightarrow Q_i \equiv q_i(t + \tau) \quad \tau \rightarrow 0$$

$$p_i(t) \equiv p_i \longrightarrow P_i \equiv p_i(t + \tau) \quad \tau \rightarrow 0$$

$$Q_i = q_i + \tau \dot{q}_i + O(\tau^2) = q_i + \tau \frac{\partial H}{\partial p_i} + O(\tau^2)$$

$$\rightarrow SA \quad G = H \quad E = t$$

Study P_i :

$$P_i = p_i + \tau \dot{p}_i + O(\tau^2) = p_i - \tau \frac{\partial H}{\partial q_i} + O(\tau^2)$$

\rightarrow works for \tilde{P}_i too!

\Rightarrow Hamiltonian dynamics is in itself just
a canonical transformation!

Consequence:

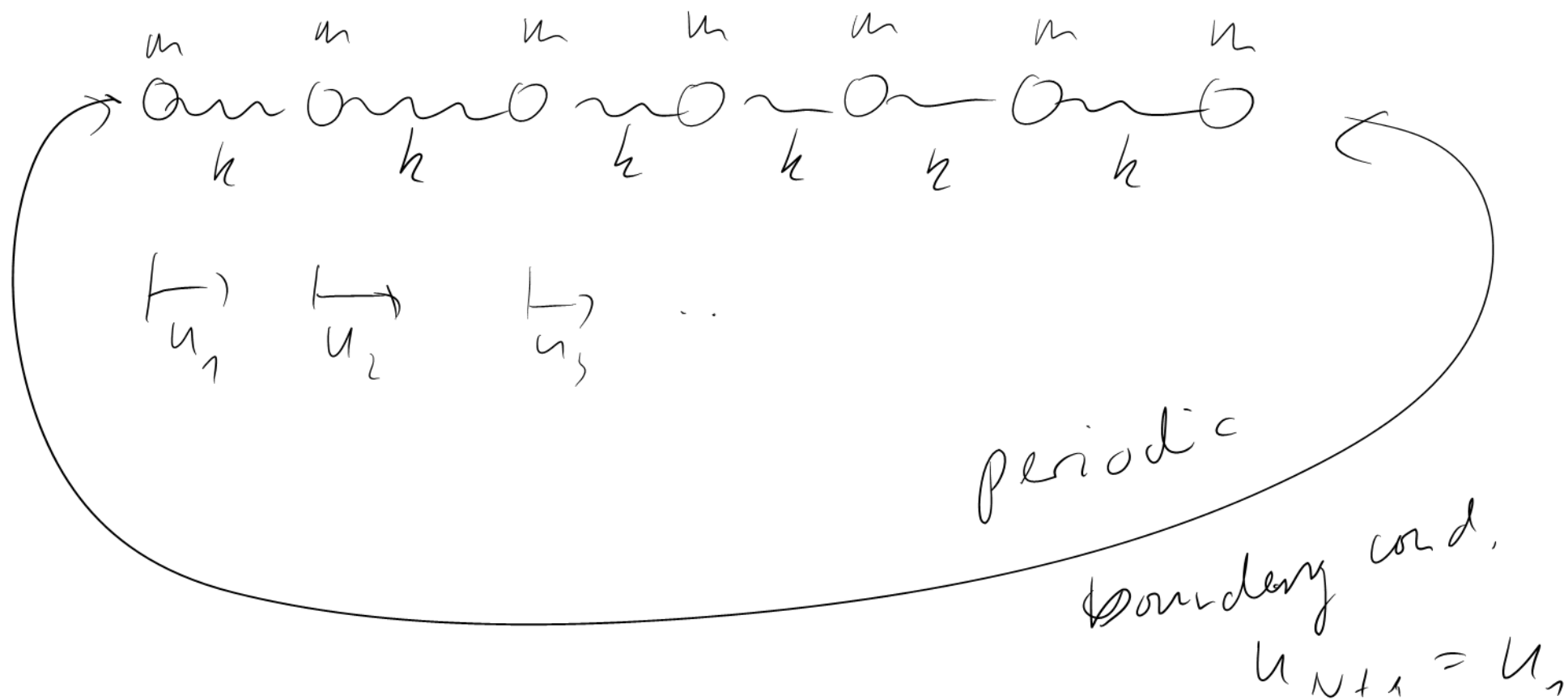
LIUVILLE'S THEOREM:

Phase space volume is invariant under

Hamiltonian dynamics!!!

FIELD THEORY

Example: Linear harmonic chain N mass points,



$$L = \frac{m}{2} (\dot{u}_1^2 + \dot{u}_2^2 + \dots + \dot{u}_N^2) - \frac{k}{2} \left[(u_2 - u_1)^2 + (u_3 - u_2)^2 + \dots + (u_N - u_{N-1})^2 + \underbrace{(u_{N+1} - u_N)^2}_{=u_1} \right]$$

$$\frac{\partial L}{\partial \dot{u}_n} = m \dot{u}_n \quad \Rightarrow \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{u}_n} \right) = m \ddot{u}_n$$

$$\frac{\partial L}{\partial u_n} = -k(u_n - u_2) - k(u_n - u_N) = -2k u_n + k u_2 + k u_N$$

$$u_i \longrightarrow u(x) \quad \sum_{i=1}^N \longrightarrow \frac{1}{a} \int_0^{Na} dx \quad Na = R$$

a : lattice spacing

$$u_{i+1} - u_i = a \frac{\partial}{\partial x} u$$

Lagrangian in the continuum limit:

$$L = \frac{1}{a} \int_0^R dx \left\{ \frac{m}{2} \dot{u}(x,t)^2 - \frac{k}{2} \left(\frac{\partial}{\partial x} u(x,t) \right)^2 a^2 \right\}$$

$$= \int_0^R dx \underbrace{\mathcal{L}(x,t)}_{\text{Lagrange density}}$$

$$\mathcal{L} = \mathcal{L}(u, \dot{u}, \frac{\partial}{\partial x} u) \quad \partial_t \equiv \frac{\partial}{\partial t}$$

cf. $L(q, \dot{q})$

$$S = \int dt \int d^3x \mathcal{L}(\varphi(\vec{r}, t), \frac{\partial}{\partial t} \varphi, \vec{\nabla} \varphi)$$

$$\delta S = \int dt \int d^3x \left\{ \frac{\partial \mathcal{L}}{\partial \varphi} \delta \varphi + \underbrace{\frac{\partial \mathcal{L}}{\partial (\vec{\nabla} \varphi)} \cdot \delta(\vec{\nabla} \varphi)}_{\text{boundary}} + \underbrace{\frac{\partial \mathcal{L}}{\partial (\partial_t \varphi)} \delta(\partial_t \varphi)}_{\text{boundary}} \right\}$$

$$= \int dt \int d^3x \left\{ \frac{\partial \mathcal{L}}{\partial \varphi} - \vec{\nabla} \cdot \frac{\partial \mathcal{L}}{\partial (\vec{\nabla} \varphi)} - \partial_t \frac{\partial \mathcal{L}}{\partial (\partial_t \varphi)} \right\} \delta \varphi$$

boundary terms vanish by suitable formulation.

Euler-Lagrange eq.:

$$\vec{\nabla} \cdot \frac{\partial \mathcal{L}}{\partial(\vec{\nabla} \varphi)} + \partial_t \frac{\partial \mathcal{L}}{\partial(\partial_t \varphi)} = \frac{\partial \mathcal{L}}{\partial \varphi}$$

$$\mathcal{L} = \frac{m}{2a} \dot{u}^2 - \frac{ka}{2} \left(\frac{\partial}{\partial x} u \right)^2 \quad \Rightarrow \quad \frac{\partial \mathcal{L}}{\partial u} = 0$$

$$\frac{\partial \mathcal{L}}{\partial(\partial_x u)} = -ka(\partial_x u) \quad \Rightarrow \quad \partial_x \frac{\partial \mathcal{L}}{\partial(\partial_x u)} = -ka \partial_x^2 u$$

$$\frac{\partial \mathcal{L}}{\partial(\partial_t u)} = \frac{m}{a} (\partial_t u) \quad \Rightarrow \quad \partial_t \frac{\partial \mathcal{L}}{\partial(\partial_t u)} = \frac{m}{a} \partial_t^2 u$$

$$\frac{m}{a} \partial_t^2 u - k a \partial_x^2 u = 0$$

$$\left(\frac{m}{k a^2} \frac{\partial}{\partial t^2} - \frac{\partial}{\partial x^2} \right) u = 0$$

wave equation

$$\frac{1}{c^2} = \frac{m}{k a^2}$$

↓

c : speed of sound

$$c^2 = \frac{k a^2}{m}$$

