

Elasticity of polyelectrolyte multilayer microcapsules

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We present a novel approach to probe elastic properties of polyelectrolyte multilayer microcapsules. The method is based on measurements of the capsule load-deformation curves with the atomic force microscope. The experiment suggests that at low applied load deformations of the capsule shell are elastic. Using elastic theory of membranes we relate force, deformation, elastic moduli, and characteristic sizes of the capsule. Fitting to the prediction of the model yields the lower limit for Young's modulus of the polyelectrolyte multilayers of the order of 1–100 MPa, depending on the template and solvent used for its dissolution. These values correspond to Young's modulus of an elastomer. © 2004 American Institute of Physics. [DOI: 10.1063/1.1644104]

I. INTRODUCTION

Recently there has been much interest in studying polyelectrolyte multilayer microcapsules.¹ These capsules are made by layer-by-layer (LbL) adsorption² of oppositely charged polyelectrolytes onto charged colloidal particles with subsequent removal of the template core³ and are important for a variety of applications such as drug delivery, catalysis, and biotechnology. At a more fundamental level, polyelectrolyte microcapsules represent a convenient system for studying the physical properties of free polyelectrolyte multilayer films. A free thin film geometry allows one to study properties not accessible in the bulk or in supported films. In this way one might gain a better understanding of polyelectrolytes in general.

Mechanical properties are among the most important and almost certainly the least understood physical properties of free multilayer films. They define deformation and rupture of the capsule shell under an external load, which is important, for instance, in the development of the delivery systems for drug injection into blood vessels.⁴ This can also help to understand the principles underlying the mechanical behavior of living cells. For example, the elastic properties of the capsule shell can be used as an input to models of penetration of particular viruses into the biological cell.⁵

There have been three recent attempts to study the mechanical behavior of polyelectrolyte microcapsules. The first involves observing osmotically induced buckling of capsules immersed in a polyelectrolyte solution.⁶ In this method the external osmotic pressure induces instability in the capsule

shape. If the capsule is highly permeable for the solvent (water), the capsule wall bends and a cuplike shape is formed. The second method is based on studying the swelling of microcapsules filled with a solution of a strong polyelectrolyte.⁷ The third attempt involves measuring the deformation of microcapsules under applied load using atomic force microscope (AFM).^{8,9} The advantage of the AFM technique is its accuracy, the possibility of studying a wider range of systems, and richer experimental information: it allows one to distinguish between different regimes in load-deformation profiles and study the permeability, elasticity, and plasticity of the capsule shell.

Motivated by a recent AFM study,^{8,9} which was focused on the *qualitative* difference between various regimes in the load-deformation profiles and on the role of encapsulated polymers, we apply the AFM approach to study *quantitatively* the elastic properties of the capsule shell. As an initial application of our method we have chosen to study capsules with shells composed of layers of alternating poly(sodium 4-styrene sulfonate) and poly(allylamine) hydrochloride. These multilayers are stable in various chemical environments. Their thickness is known to grow linearly with the number of deposited bilayers, so that they represent a convenient system for verification of our approach. Beside that this type of the shell was used in the previous studies of mechanical properties of the capsules.^{6–9} We work in a small deformation regime, which allows one to treat capsule deformations as elastic. By fitting load-deformation curves to the predictions of a simple model we are able to obtain the lower limit for Young's modulus of the polyelectrolyte multilayer complex forming the capsule shell.

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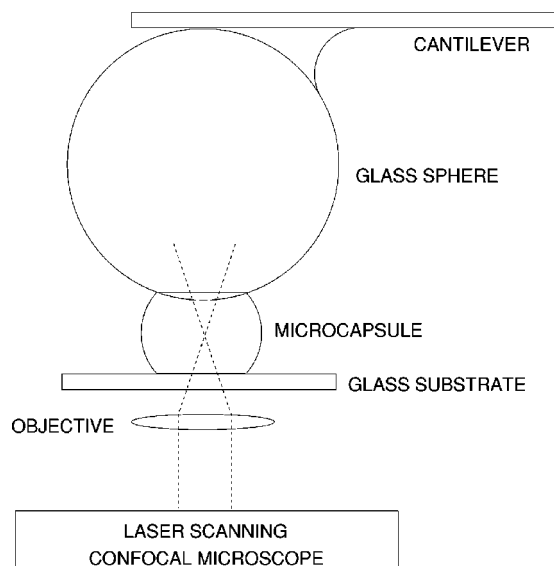


FIG. 1. Schematic of the AFM force experiment.

II. MATERIALS AND METHODS

The capsules were produced according to the method^{3,10} based on LbL assembly of several bilayers of polystyrene sulfonate (PSS, $M_w \sim 70\,000$, Aldrich) and poly(allylamine) hydrochloride (PAH, $M_w \sim 50\,000$, Aldrich) on a weakly cross-linked (latex) template. As a template we used suspensions of polydisperse poly-DL-lactic acid (PLA) particles and monodisperse melamine formaldehyde (MF) particles purchased from Microparticles GmbH (Berlin, Germany). The PLA particles were of a radius in the range from 2 to 8 μm and were dissolved using a 1:1 mixture of (1-methyl-2-pyrrolidinone) acid and organic solvent (acetone) after the assembly of four PSS/PAH bilayers.¹⁰ This type of capsule is referred to below as PLA capsules. The MF particles were of radius $2.0 \pm 0.1 \mu\text{m}$ and were dissolved using HCl (at $p\text{H}$ 1.2–1.4) to give so-called MF capsules. The variation of shell thickness was achieved by two methods. In the first method we varied the number of bilayers deposited on MF templates. In the second method we dissolved the MF particles after deposition of the fourth bilayer. Then several additional bilayers were deposited to tune the final shell thickness.

Load (force) versus deformation curves were measured with the molecular force probe (MFP) 2D AFM (Asylum Co, Santa Barbara, CA) equipped with a nanopositioning sensor that corrects piezoceramic hysteresis and creep. The MFP was used together with a commercial confocal microscope manufactured by Olympus (Japan) consisting of the conconfocal laser scanning unit Olympus FV 300 in combination with an inverted fluorescence microscope Olympus IX70 equipped with a high-resolution immersion oil objective ($60\times$). The confocal microscope was specially adjusted for the MFP 2D. This allowed simultaneous optical measurements of the capsule's shape during the AFM force experiment. The excitation wavelength was chosen according to the label rhodamine (543 nm). The z -position scanning was done in steps of $0.05 \mu\text{m}$.

A schematic of the experiment is presented in Fig. 1. A drop ($50\text{--}100 \mu\text{l}$) of water (purified by a commercial milli-Q

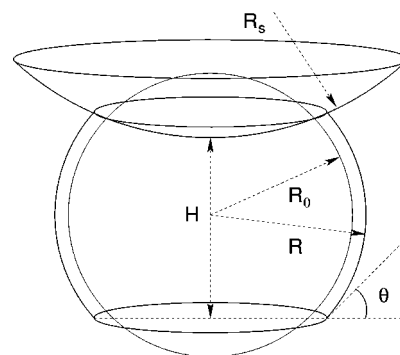


FIG. 2. Sketch of the microcapsule: undeformed and deformed states. If the volume of the deformed capsule remains constant (no water drainage through the capsule shell), then the increase in the capsule radius is quadratic in the relative deformation $\epsilon = 1 - H/(2R_0)$ [see Eq. (1)].

gradient A10 system containing ion exchange and charcoal stages) suspension of polyelectrolyte microcapsules was deposited onto a thin glass slide fixed over the oil immersion objective of the confocal microscope. The glass sphere (radius $R_s = 20 \pm 1 \mu\text{m}$, Duke Sci. Co., Palo Alto, CA) attached to a cantilever (V-shaped, Micromash, Estonia, spring constants $k = 2.5 \text{ N/m}$) was centered above the apex of a capsule with accuracy of $\pm 0.5 \mu\text{m}$, using the graticule lines in the optical image for alignment. Measurements were performed at a speed in the range from 0.2 to 20 $\mu\text{m/s}$.

The result of measurements represents the deflection Δ versus the position of the piezotranslator at a single approach (loading). The load \mathcal{F} was determined from the cantilever deflection, $\mathcal{F} = k\Delta$. As before, we assume that the zero of separation is at the point of the first measurable force.⁸ Then the deformation is calculated as the difference between the position of the piezotranslator and cantilever deflection.

The diameters of the capsules were determined optically with the accuracy of $0.4 \mu\text{m}$ and from the AFM load versus deformation curves (see Ref. 8 for more details). The relative deformation ϵ of the capsule was then defined as $\epsilon = 1 - H/(2R_0)$ (see Fig. 2), where R_0 is the radius of the undeformed capsule.

III. RESULTS

A. MF capsules

The three-dimensional (3D) confocal scanning suggested that undeformed capsules have spherical shape [Fig. 3(a)].

Figure 4 shows typical for MF capsules (loading/unloading) deformation profiles for small relative deforma-



FIG. 3. Typical confocal images of MF capsules (radius $R_0 = 2 \mu\text{m}$) obtained for different stages of deformation: (a) $\epsilon = 0$, (b) $\epsilon = 0.2$, and (c) $\epsilon = 0.5$.

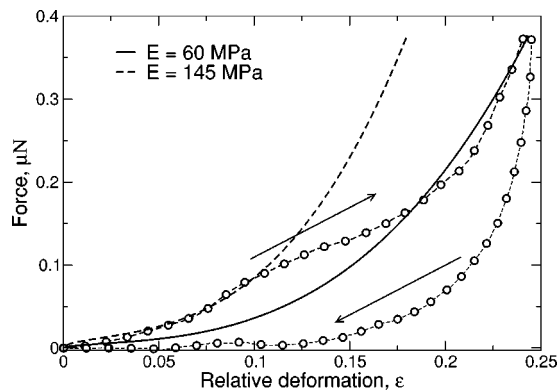


FIG. 4. Typical loading/unloading curves for MF capsules (radius $R_0 = 2 \mu\text{m}$). Driving speed $v = 20 \mu\text{m/s}$. Fit to Eq. (14) gives an estimate for the Young's modulus in the range $E \approx 60\text{--}150 \text{ MPa}$.

tions ($\epsilon \approx 0.2\text{--}0.3$). By analyzing these profiles and images of confocal scanning we found the following.

(i) The deformation is completely reversible. In other words, the capsule always returns to its original state (the force vanishes at zero deformation) during consequent loading/unloading cycles. No deviation of the free area of the capsules from the spherical shape was found within the accuracy of confocal measurements [Figs. 3(a) and 3(b)].

(ii) The pull-off force is equal to zero.

(iii) The load-deformation profiles do not depend on the driving speed.

(iv) The loading/unloading has hysteresis; i.e., force upon retraction is less than on approach at the same relative deformation. This loading/unloading hysteresis is relatively small.

For relative deformations $\epsilon \geq 0.2\text{--}0.3$ we observed large hysteresis, only partial reversibility in loading/unloading, noisy regions in the deformation profiles, and significant dependence on the driving speed, which indicates drainage of the inner solution through the shell and/or its local ruptures. This is also confirmed by a confocal 3D scanning [Fig. 3(c)].

The load at a fixed relative deformation for MF capsules with different shell thickness h is presented in Fig. 5. The

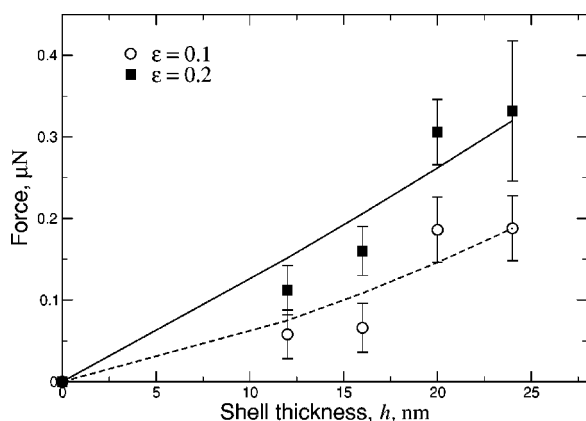


FIG. 5. Load vs shell thickness for MF capsules of $R_0 = 2 \mu\text{m}$. Circles: relative deformation $\epsilon = 0.1$. Squares: $\epsilon = 0.2$. Fit to Eq. (14) gives $E \approx 60 \text{ MPa}$ for $\epsilon = 0.2$, and $E \approx 180 \text{ MPa}$ for $\epsilon = 0.1$. Measurements were performed at the driving speed $20 \mu\text{m/s}$.

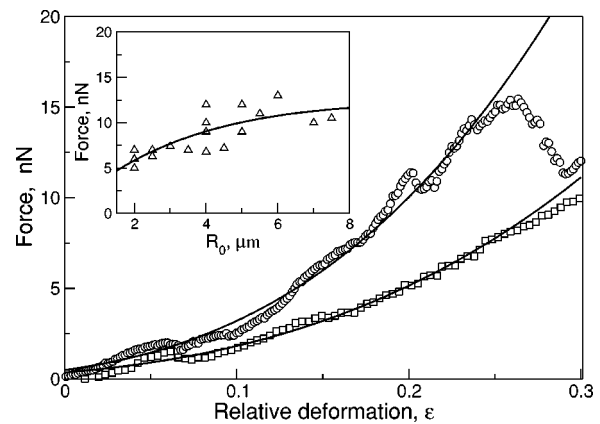


FIG. 6. Load vs deformation curves for PLA capsules of different size (symbols) and their fit to Eq. (14) (solid curves). Squares: $R_0 = 2 \mu\text{m}$. Circles: $R_0 = 5 \mu\text{m}$. The inset shows the force at a fixed relative deformation, $\epsilon = 0.2$, as a function of the capsule radius. Measurements were performed at the driving speed $2 \mu\text{m/s}$.

value of h was calculated as a product of the number of PSS/PAH bilayers in the shell and a thickness of one bilayer. The values reported for a bilayer thickness vary in the range $\approx 3\text{--}5 \text{ nm}$.^{3,11} Here we use the average value of 4 nm . Analysis of data presented in Fig. 5 suggests that the capsules are getting stiffer with the increase in the shell thickness and that the effect of the shell thickness depends on the relative deformation ϵ .

B. PLA capsules

By performing the same force and optical measurements we have made exactly the same conclusions as for MF capsules. PLA capsules have, however, been found to be much softer (weaker force at the same ϵ), with much smaller hysteresis; i.e., the loading branch of the force was much closer to the unloading one.

With the PLA capsules we were able to investigate the effect of the capsule size. Analysis of the load-deformation curves (Fig. 6) showed that bigger capsules are stiffer than smaller ones. The inset of Fig. 6 shows the force at a fixed relative deformation as a function of the capsule radius. Each point corresponds to a different capsule. The scatter in the force is due to the variation of the properties of the capsule shell, which changes slightly from capsule to capsule (the actual error of our force measurements was about 0.5 nN).

IV. DISCUSSION

A simple model accounts for these experimental observations. Since hysteresis is small and the load-deformation profiles do not depend on the driving speed (in the interval used), we can, in the first approximation, neglect drainage of the water through the capsule shell and assume that the volume of the capsule does not change on short time scale of the AFM experiment.

To relate the relative deformation ϵ and the change in the capsule radius we further assume that, for small deformations, the shape of the capsule remains spherical except in the contact regions¹² (see Fig. 2). Then, for small ϵ , volume conservation requires

$$R = R_0 + \frac{R_0}{2} \frac{1 + R_0/(2R_s)}{(1 + R_0/R_s)^2} \epsilon^2 + \mathcal{O}(\epsilon^3), \quad (1)$$

where R is the final radius of the capsule. Equation (1) shows that the increase in the capsule radius is quadratic in the relative deformation ϵ .

Note that there are two dimensionless parameters in Eq. (1). The first one is the relative deformation, ϵ . Deriving Eq. (1) we expanded $R - R_0$ in powers of ϵ and left only the lowest, quadratic in ϵ , term of the expansion. The second parameter is the ratio of the glass sphere and the capsule radii, R_0/R_s . No expansion was made with respect to this ratio. However, when deriving Eq. (1), we implicitly assumed that the radii of the contact areas of the glass sphere and glass substrate are equal, which is justified provided R_0 is at least several times smaller than R_s .

Since capsule deformations are small and reversible, we can use the elastic theory of membranes to find the restoring force. The elastic energy of the stretching of the membrane reads¹³

$$G = \frac{h}{2} \int u_{\alpha\beta} \sigma_{\alpha\beta} dS, \quad (2)$$

where the Einstein summation convention is implied, integration is over the membrane's surface, $u_{\alpha\beta}$ is a two-dimensional deformation tensor, and $\sigma_{\alpha\beta}$ is two-dimensional stress tensor:

$$\sigma_{\alpha\beta} = \frac{E}{1 - \nu^2} [(1 - \nu)u_{\alpha\beta} + \nu \delta_{\alpha\beta} u_{\gamma\gamma}], \quad (3)$$

where E is Young's modulus, ν is Poisson's ratio, and summation over repeating indices is assumed.

Balance of stresses defines the pressure P inside the capsule:

$$P = \frac{h}{R} (\sigma_{\theta\theta} + \sigma_{\phi\phi}). \quad (4)$$

Using the relation between the stress and deformation tensors,

$$Eu_{\theta\theta} = \sigma_{\theta\theta} - \nu\sigma_{\phi\phi}, \quad (5)$$

$$Eu_{\phi\phi} = \sigma_{\phi\phi} - \nu\sigma_{\theta\theta}, \quad (6)$$

as well as the assumption that the deformed capsule has spherical shape,

$$u_{\theta\theta} = u_{\phi\phi} = \frac{u_r}{R} = \frac{R - R_0}{R}, \quad (7)$$

we obtain

$$\sigma_{\theta\theta} = \sigma_{\phi\phi} = \frac{E}{1 - \nu} \frac{R - R_0}{R}. \quad (8)$$

Substituting Eqs. (7) and (8) to Eq. (2) we obtain the elastic energy due to the capsule stretching:

$$G_s \approx 4\pi \frac{E}{1 - \nu} h(R - R_0)^2. \quad (9)$$

Correspondingly, the reaction force (load)

$$\mathcal{F}_s = -\frac{\partial G_s}{\partial H} = 2\pi \frac{E}{1 - \nu} h R_0 \frac{[1 + R_0/(2R_s)]^2}{(1 + R_0/R_s)^4} \epsilon^3 \quad (10)$$

has cubic dependence on the relative deformation ϵ . For small microcapsules—i.e., when $R_0/R_s \ll 1$ —the force at fixed relative deformation is simply proportional to the capsule radius R_0 . The alternative (and equivalent) way to obtain the reaction force is to multiply the pressure P from Eq. (4) by the microcapsule–glass–sphere contact area.

Note that here we ignored the contribution to the elastic energy due to shell bending. This is reasonable, for a very thin membrane, everywhere except near the line separating the capsule, glass sphere/substrate, and the exterior (the edge of the contact area). An exact treatment of bending effects is rather complicated; the bending moment could perturb the spherical shape of the membrane near a contact, etc. However, simple estimates of the bending energy can be made. The change from the membrane in contact with the glass sphere to the free membrane, at a contact angle θ , occurs over a length comparable to the shell thickness, h . Then the local radius of curvature of the membrane near the separation line is of the order of $\rho \approx h/\theta$.^{13,14} The elastic energy of bending, G_b , can be estimated from the beam theory:¹⁴

$$G_b \approx \frac{EI}{2} \frac{hl}{\rho^2}, \quad (11)$$

where $I = h^3/12$ is the second moment of area of the “beam” cross section, and $l = 4\pi R \sin \theta \approx 4\pi R \theta$ is the total length of the line separating the capsule, glass, and substrate. Substituting this back to the expression for the bending free energy, Eq. (11), and taking into account the volume conservation requirement $R - R_0 \approx R_0 \theta^4$, we obtain

$$G_b \approx \frac{\sqrt{2}\pi}{3} E h^2 R_0 \epsilon^{3/2}. \quad (12)$$

The reaction force due to shell bending reads

$$\mathcal{F}_b = -\frac{\partial G_b}{\partial H} = \frac{\pi}{2\sqrt{2}} E h^2 \epsilon^{1/2}. \quad (13)$$

Comparing the reaction forces due to stretching and bending, Eqs. (10) and (13), one can conclude that, for typical experimental values $h = 20$ nm, $R_0 = 2$ μ m, bending is negligibly small for relative deformations $\epsilon \geq 0.15$.

The total reaction force (load) for $R_s \gg R_0$ and $\nu = 1/2$ (typical value for elastomer materials¹²) reads

$$\mathcal{F} = \frac{\pi}{2\sqrt{2}} E h^2 \epsilon^{1/2} + 4\pi E h R_0 \epsilon^3. \quad (14)$$

We fitted the load-deformation profiles for PLA capsules to Eq. (14) taking the Young's modulus E as a fitting parameter. Only the data for the capsules with $R < 5$ μ m were used to ensure that $R_s \gg R_0$. The fitting curves, together with the experimental data, are shown in Fig. 6. The value $E = 1 \pm 0.5$ MPa was obtained from fitting.

For sufficiently large relative deformations $\epsilon \geq 0.15$, when we can safely neglect shell bending, our model also predicts the dependence of the reaction force on the capsule

radius, given by the prefactor in Eq. (10), which depends on R_0 . This prediction is indeed confirmed by the experiment, as shown in the inset of Fig. 6.

For MF capsules, prepared in the acid media without adding any solvent or organic acid, we obtained Young's modulus of the shell of the order of 100 MPa. The experimental dependence of the load on the shell thickness is consistent with our model (Fig. 5) and confirms that bending is important only at very low ϵ . We also analyzed previously obtained data for MF capsules of the same chemical composition, but prepared by dissolution of a template in a more aggressive acid media (3 mol/l HCl).^{8,9} For these capsules we obtained a Young's modulus of the PSS/PAH shell of the order of 30 MPa, and even a smaller value for the same capsules, but after treatment in organic solvent (water/acetone mixture).⁹

V. CONCLUSIONS

Several remarks can be made in conclusion:

First, the Young's modulus obtained here is at least one order of magnitude lower than in the experiment on osmotically induced deformation of PSS/PAH capsules made on the MF template.⁶ It can be argued that the theory of osmotically induced shape transitions (buckling) of the capsules used in Ref. 6 ignores the finite permeability of the shell membrane to water. However, it is clear that the finite permeability stabilizes a spherical shape of the capsule, leading to higher values of critical osmotic pressure (infinite for zero permeability) or, equivalently, to smaller values of Young's modulus. The consequences of overestimation of Young's modulus in Ref. 6 are very important. It led, in particular, to the conclusion that multilayers represent quite a rigid material comparable with the *bulk plastics*.¹⁵ Contrary to this, our experiment demonstrated that the value of the Young's modulus of the multilayer corresponds to that of *elastomers*.¹⁵ It is likely that the approach (model) we used here underestimates the value of Young's modulus, because it neglects the drainage of water from the capsule. These values (1–100 MPa), therefore, give the lowest limit for Young's modulus of polyelectrolyte multilayers. However, our results strongly support the conclusions of the recent swelling experiment,⁷ which has given a slightly larger, but of the same order of magnitude, value for E . We have argued,⁷ that the osmotically induced swelling measurements give the upper limit for Young's modulus. Therefore, taken together, these two types of experiment provide the range of possible values for Young's modulus of a PSS/PAH multilayer.

Second, the PLA capsules are one or two order of magnitudes softer than MF capsules.⁸ This is likely due to organic solvent and the different (and more concentrated) acid used for a dissolution of the PLA templates. Similar effect is

probably responsible for the softening of MF capsules made in different conditions.^{8,9} Thus, our results suggest that the polyelectrolyte multilayers are extremely sensitive to chemical treatment. The effect of softening of the multilayer shell could be due to either structure changes or partial dissolution of the shell, and is poorly understood at the moment.⁹

Third, the capsules behave as non-Hookean (nonlinear) springs even in the weak force regime, contrary to most similar systems which respond as Hookean springs to applied loads.¹⁶

Fourth, the adhesion force does not affect the determination of Young's modulus. Indeed, as follows from the model, the area of the contact (and the adhesion energy) is proportional to the relative deformation ϵ . Therefore, the contribution to the force due to adhesion does not depend on ϵ and will only uniformly shift the load-deformation profiles.

In summary, using the AFM technique, we were able to estimate the Young's modulus of the molecularly thin polyelectrolyte multilayer, which was found to be of the order of a 1–100 MPa. We also demonstrated that the elastic properties of the multilayer shell can be modified by treatment in a solvent and acid, and depends on the template used for the capsule preparation.

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